Demixed PCA, or how to tie dimension reduction to experimental conditions

Mihály Bányai Population Activity Study Group MTA KOKI, 04.15. 2016.

Demixed Principal Component Analysis

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Demixed principal component analysis of population activity in higher cortical areas reveals independent representation of task parameters

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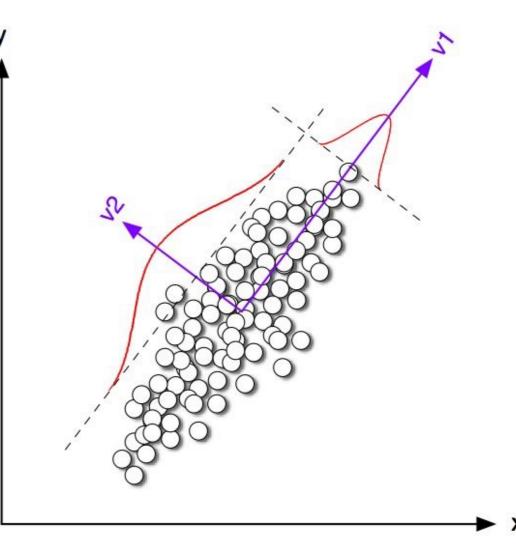
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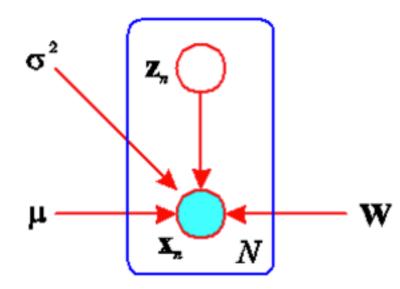
Augmenting dimensionality reduction

- When looking for a lower dimensional representation of your data, you typically enforce generic principles about the latent variables
 - independence, orthogonality, sparsity, etc.
 - these may correspond to stimulus features or experimental conditions, but not necessarily (especially given the structure of your model, e.g. linear mappings)
- Another approach is to put conditions explicitly in the model

Review of PCA

- goal: explain as much variance with as few variables (components) as possible
- parameter estimation: eigenvectors of data covariance matrix
 - or an iterative Expectation Maximisation parameter estimation algorithm



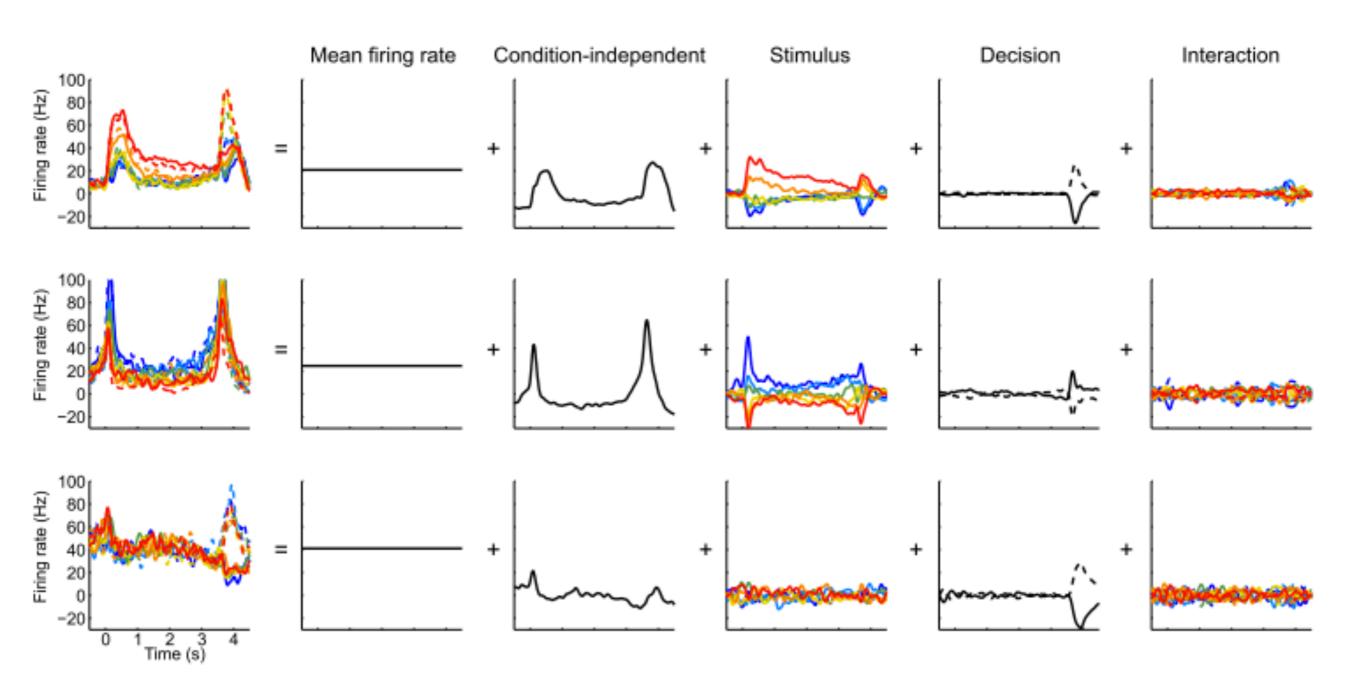


$$p(z) = \mathcal{N}(z; 0, \mathbf{I})$$
$$p(x \mid z) = \mathcal{N}(x; \mathbf{W}z + \mu, \sigma^{2}\mathbf{I})$$

Data

- four different datasets from the labs of Romo, Constantinidis and Mainen
- monkey PFC, rat OFC
 - decision tasks, in each trial there is a stimulus (tactile, visual or olfactory) and the animal makes a binary decision
- they always use the peristimulus time histogram as data
 - they average over trials (needed because cells are not recorded simultaneously, and have diff. number of trials too)
 - data dimension: #cells x (#stim · #dec · #timebin)

Demixing



Decomposition of variance

 If we decompose the data by marginalising over different parameters, the covariance matrix can be given as a sum of the decomposed covariances

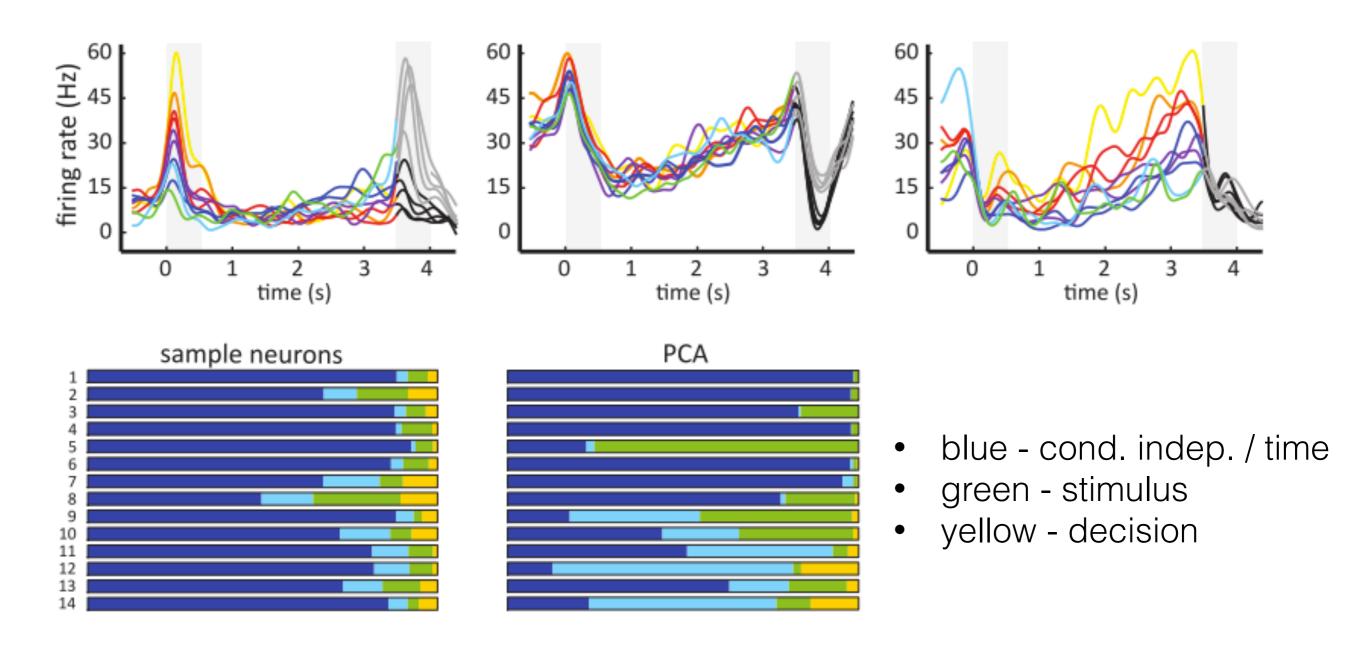
 $x(t,s) = \mu + z(t) + z(s) + z(t,s).$

$$z(t) = \langle x(t,s) - \mu \rangle_s. \qquad z(s) = \langle x(t,s) - \mu \rangle_t. \qquad z(t,s) = x(t,s) - \mu - z(t) - z(s).$$

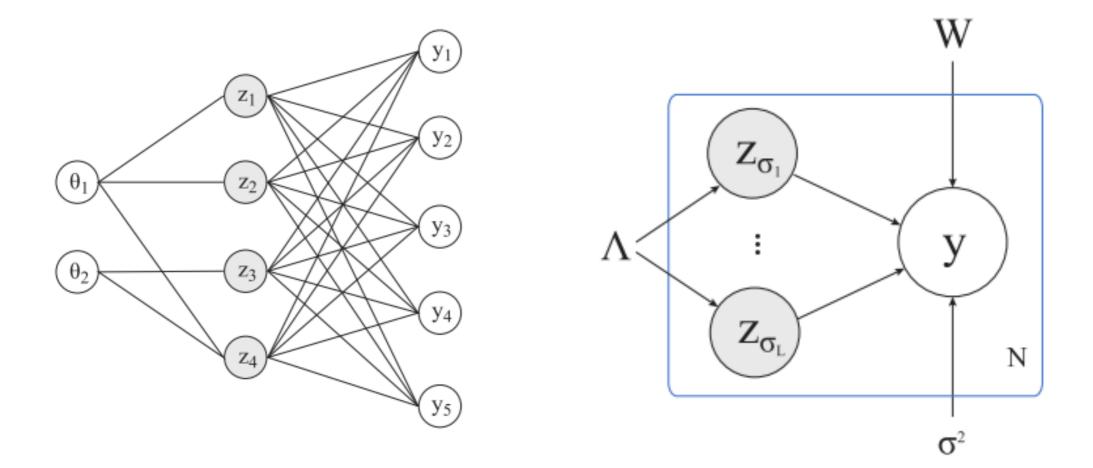
 $\operatorname{Var}(x(t,s)) = \operatorname{Var}(z(t)) + \operatorname{Var}(z(s)) + \operatorname{Var}(z(t,s)).$

 Instead of regular principal components, we are looking for ones that describe variance only in the direction of the eigenvectors of one of the decomposed covariances

Selectivity of neurons and principal components

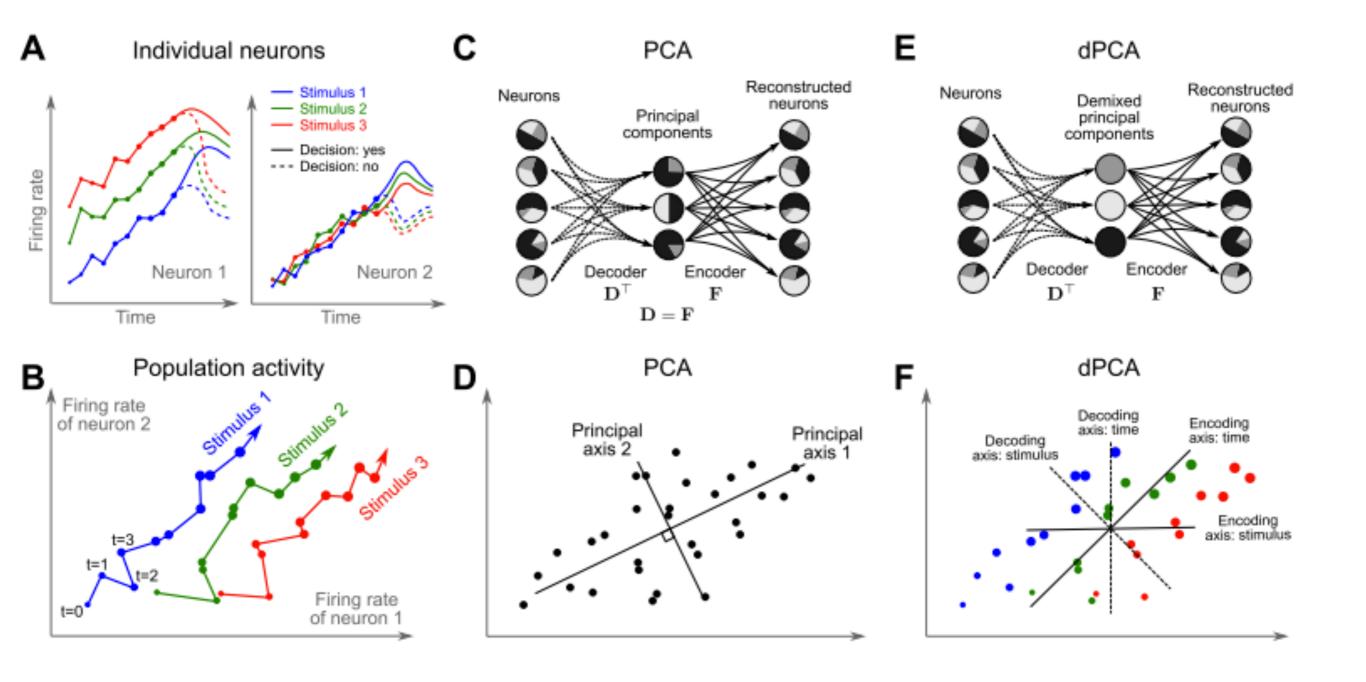


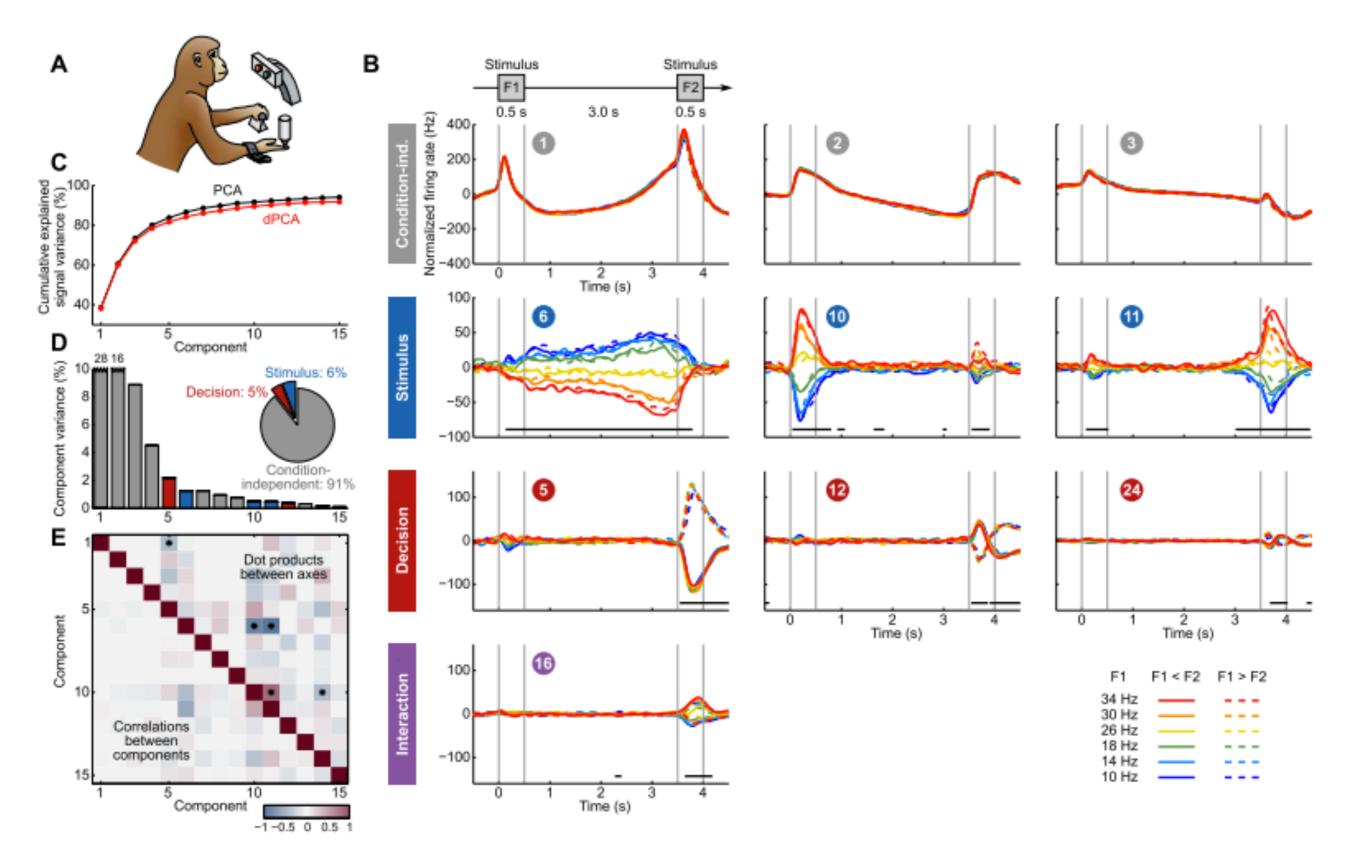
Generative model of dPCA



 An EM algorithm can be derived to find the components by adding constraints to the standard PCA inference

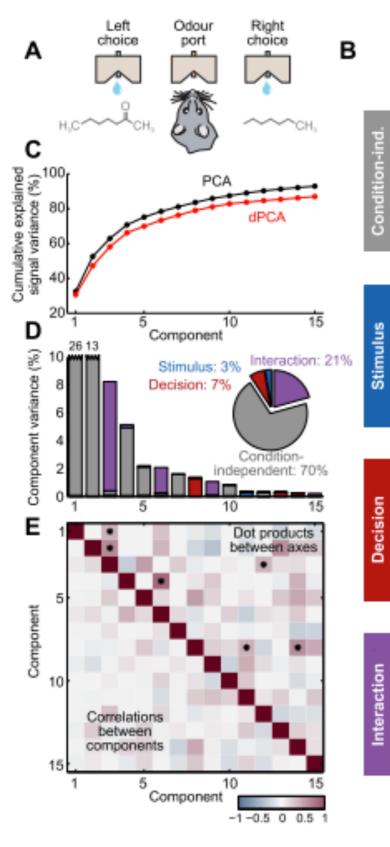
PCA vs. dPCA

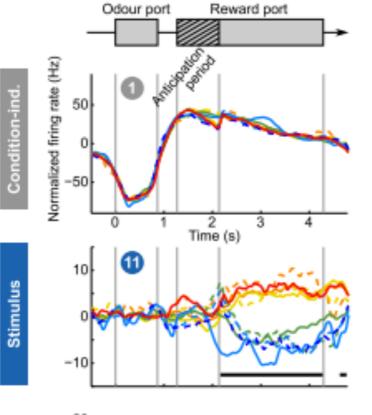


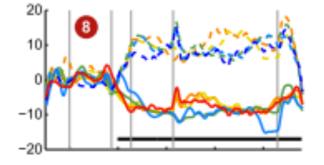


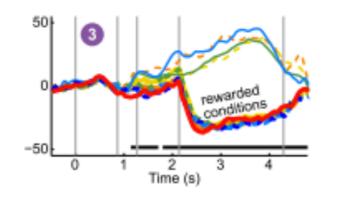
Insights

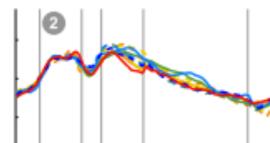
- Linear demixing of the population activity is possible
- Most of the variance is explained by components not related to any conditions
- Some components are the derivatives of each other -> similar activity patterns arise in the population with temporal shifts
- Using decision-related components as fixed linear decoders, one can decode the decision from the population activity with ~75% accuracy

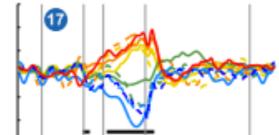


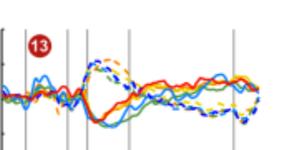




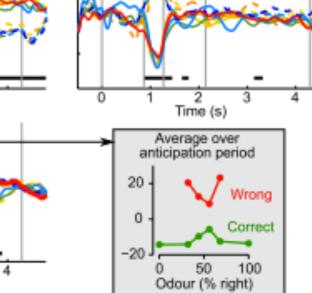


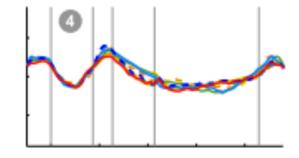


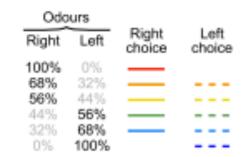




Time (s)







Limitations

- Needs lots of neurons
- All parameter combinations need to be present in the data
- Applied only to PSTH here, in theory it might be applicable to trial-to-trial covariability, but not tested

Functional generative models vs. demixed dimensionality reduction

- Generative models of perception
 - neural activation / latent causes -> stimulus
 - emphasis on prediction of neural activity statistics
- Demixed dimension reduction
 - stimulus / conditions -> neural activation
 - emphasis on identification of variable mappings
- Hypotheses about neural representations are formalisable in both frameworks