

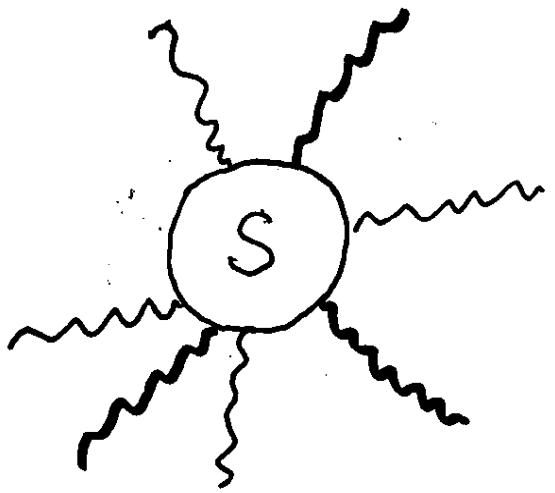
~~Intrinsic time in Markovian Open Systems~~

Total Disentanglement by Markovian Open System Dynamics (Lajos Diósi, Budapest)

- von Neumann-measurement
 - Disentanglement
 - " - of qbits
 - " - of particles
 - Wigner function ≥ 0
 - P-function ≥ 0
 - Conclusion
- } in finite time

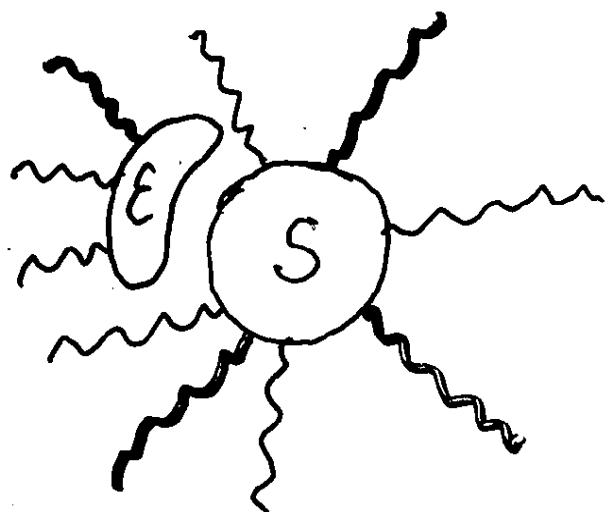
Piombino, 3 Sept 2002

1a

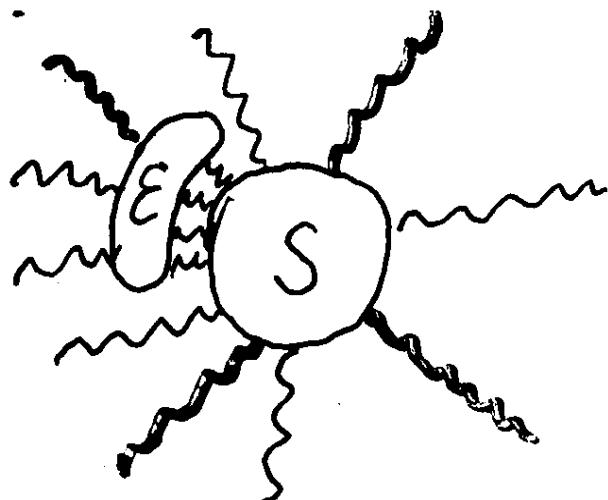
 $t < 0.$

classical
correlation

quantum
correlation

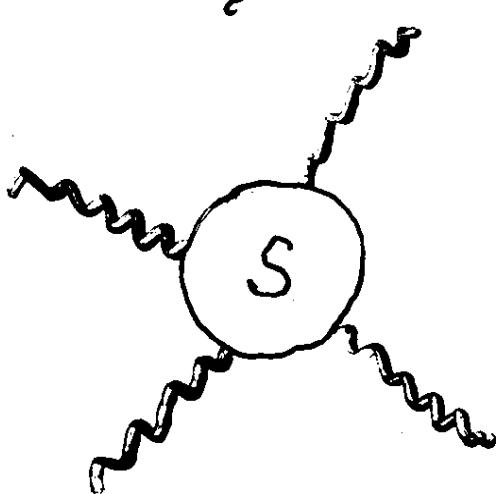
 $t = 0$

System
Environment
Rest Of Universe



$$\frac{d}{dt} \hat{\rho}_S = \mathcal{L} \hat{\rho}_S$$

$$t \in [0, t_D]$$

 $t > t_D$

$$\hat{\rho}_{S+ROU} = \sum_{\lambda} p_{\lambda} \hat{\rho}_S^{\lambda} \otimes \hat{\rho}_{ROU}^{\lambda}$$

$$p_{\lambda} \geq 0; \sum_{\lambda} p_{\lambda} = 1$$

VonNeumann-measurement

$$\hat{\rho} \rightarrow \sum_{\lambda} \hat{P}^{\lambda} \hat{\rho} \hat{P}^{\lambda} \quad \begin{aligned} \hat{P}^{\lambda} &> 0, \sum \hat{P}^{\lambda} = \hat{I} \\ [\hat{P}^{\lambda}, \hat{P}^{\mu}] &= 0 \end{aligned}$$

attributes objective classical properties to the post-measurement state.

The diagonal form

$$\hat{\rho} = \sum_{\lambda} \hat{P}^{\lambda} \hat{\rho} \hat{P}^{\lambda}$$

in itself wouldn't be enough since $\hat{\rho}$ may still be q-correlated with ROU.

This is not in vN's book:

$$\hat{\rho}_v \rightarrow \sum_{\lambda} (\hat{P}^{\lambda} \otimes \hat{I}_{\text{ROU}}) \hat{\rho}_v (\hat{P}^{\lambda} \otimes \hat{I}_{\text{ROU}})$$

but should be understood!

vN measurement diagonalizes
&
disentangles*

* to the extent needed for objective classical prop's.

(3)

Local maps that disentangle

Definition: $\hat{\rho}$ is disentangled from the RestOftheUniverse if

$$\hat{\rho}_U = \sum_{\lambda} p_{\lambda} \hat{P}^{\lambda} \otimes \hat{P}_{ROU}^{\lambda}$$

$$p_{\lambda} > 0, \sum_{\lambda} p_{\lambda} = 1$$

Theorem: $\hat{\rho} \rightarrow M\hat{\rho}$ disentangles all $\hat{\rho}$ from the RestOftheUniverse

iff

$$M\hat{\rho} = \sum_{\lambda} \hat{P}_{\lambda} \text{tr}(\hat{P}^{\lambda} \hat{\rho})$$

M. Horodecki,
Shor (2002)

$$\hat{P}^{\lambda} \geq 0, \sum_{\lambda} \hat{P}^{\lambda} = \hat{I} \quad \text{i.e.: } \{\hat{P}^{\lambda}\} \text{ is POVM}$$

(4)

Markovian disentanglement of spin- $\frac{1}{2}$
 $\hat{\rho}(0)$ arbitrary, maybe entangled with ROU

"free" spin
in
isotropic
bath

$$\frac{d}{dt} \hat{\rho} = \frac{1}{4} \hat{\vec{\sigma}} \hat{\rho} \hat{\vec{\sigma}} - \frac{3}{4} \hat{\rho}, \quad t \geq 0$$

$$\rightsquigarrow \hat{\rho}(t) \equiv M(t) \hat{\rho}(0)$$

$$= \frac{1}{2} \left[\hat{I} + e^{-t} \hat{\vec{\sigma}} \operatorname{tr}[\hat{\vec{\sigma}} \hat{\rho}(0)] \right]$$

$M(t)$ totally disentangles from ROU

iff

$$M(t) = \sum_{\lambda} \hat{\rho}^{\lambda} \operatorname{tr}(\hat{\rho}^{\lambda})$$

Try this: $\lambda = (\alpha, s); \alpha = x, y, z; s = \pm 1$

$$\hat{\rho}^{(\alpha, s)} = \frac{1}{2} \left(\hat{I} + 3s e^{-t} \hat{\sigma}_{\alpha} \right)$$

$$\hat{\rho}^{(\alpha, s)} = \frac{1}{6} \left(\hat{I} + s \hat{\sigma}_{\alpha} \right)$$

Condition $\hat{\rho}^{(\alpha, s)} \geq 0 \Rightarrow t \geq \log 3$

Total disentanglement for $t \geq t_0 \log 3$

(5)

Markovian disentanglement of a particle
 $\hat{\rho}(0)$ is arbitrary

free in frictionless bath $\frac{d\hat{\rho}}{dt} = -i \left[\frac{\hat{P}^2}{2m}, \hat{\rho} \right] - \frac{D}{2} [\hat{x}, [\hat{x}, \hat{\rho}]] ; t \geq 0$

$$t_0 = \sqrt{m/D} = \text{decoherence time}$$

One expects that $\hat{\rho}(t)$ gets disentangled for $t \gtrsim t_0$.

Proof:

- $W(x, p; t) \geq 0$ if $t > 3^{1/4} t_0$
- $P(x, p; t) \geq 0$ if $t > 1.9 t_0$
- $M(t) : \hat{\rho}(0) \rightarrow \hat{\rho}(t)$ disentangles

> 1987
 Halliwell, Zoupas 1995
 Siever & D. 2001

Khalilov & Tsitrinson 1992